

1. Let P be the point $(0, 2, 1)$, and Q be the point $(-1, 3, 5)$.

(a) Write a vector parametrization of the line segment \overline{PQ} .

Solution: The vector \overrightarrow{PQ} is $\langle -1, 1, 4 \rangle$, so the parametrization we want is

$$\vec{r}(t) = -t\vec{i} + (2 + t)\vec{j} + (1 + 4t)\vec{k}, \quad 0 \leq t \leq 1.$$

(b) Find the area and the perimeter of triangle whose vertices are P , Q , and the origin.

Solution: To begin, we find the cross product of $\langle 0, 2, 1 \rangle$ and $\langle -1, 3, 5 \rangle$. We get $\langle 7, -1, 2 \rangle$. The area of the triangle is one half the magnitude of this cross product, that is $\frac{\sqrt{54}}{2}$.

To find the perimeter, we need the lengths of the sides. Denoting the origin by O , we have $|OP| = \sqrt{5}$, $|OQ| = \sqrt{35}$ and $|PQ| = \sqrt{18}$. The perimeter of the triangle is $\sqrt{5} + \sqrt{35} + \sqrt{18}$.

2. Let p_1 be the plane $2x + 4y - z = 5$ and p_2 be the plane $x - 3y - 2z = 2$.

(a) Find a vector parametrization for the line of intersection of p_1 and p_2 .

Solution: Let \vec{n}_1 and \vec{n}_2 be normal vectors to planes p_1 and p_2 respectively. We may take $\vec{n}_1 = \langle 2, 4, -1 \rangle$ and $\vec{n}_2 = \langle 1, -3, -2 \rangle$.

The line of intersection of p_1 and p_2 must be perpendicular to both \vec{n}_1 and \vec{n}_2 , so its direction is given by

$$\vec{n}_1 \times \vec{n}_2 = \langle -11, 3, -10 \rangle.$$

To find a point on the line of intersection, we need to find (x, y, z) satisfying the equations $2x + 4y - z = 5$ and $x - 3y - 2z = 2$. We arbitrarily set $y = 0$ to get the system

$$\begin{array}{rcl} 2x & - & z = 5 \\ x & - & 2z = 2 \end{array}$$

The solution is $x = \frac{8}{3}$, $z = \frac{1}{3}$. The point $\left(\frac{8}{3}, 0, \frac{1}{3}\right)$ lies on the line, and we can write a vector parametrization of the intersection line as

$$\vec{r}(t) = \left(\frac{8}{3} - 11t\right)\vec{i} + 3t\vec{j} + \left(\frac{1}{3} - 10t\right)\vec{k}.$$

(b) Find the cosine of the angle of intersection of the planes p_1 and p_2 .

Solution: Let θ denote the angle of intersection. We have

$$\begin{aligned} \cos \theta &= \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1| |\vec{n}_2|} \\ &= -\frac{8}{\sqrt{21}\sqrt{14}} \\ &= -\frac{8}{7\sqrt{6}}. \end{aligned}$$

3. Let ℓ be the line with parametric equations

$$\begin{aligned}x &= 2t \\y &= -2t \\z &= -t\end{aligned}$$

and let $\vec{v} = \langle 2, -5, 6 \rangle$. Find vectors \vec{a} and \vec{b} so that \vec{a} is parallel to ℓ , \vec{b} is perpendicular to ℓ , and $\vec{a} + \vec{b} = \vec{v}$.

Solution: The vector \vec{a} that we want is just the vector projection of \vec{v} onto the direction vector of ℓ , which is $\langle 2, -2, -1 \rangle$. We have

$$\begin{aligned}\vec{a} &= (\vec{v} \cdot \langle 2, -2, -1 \rangle) \frac{\langle 2, -2, -1 \rangle}{9} \\&= \frac{8}{9} \langle 2, -2, -1 \rangle \\&= \left\langle \frac{16}{9}, -\frac{16}{9}, -\frac{8}{9} \right\rangle.\end{aligned}$$

Then \vec{b} is simply $\vec{v} - \vec{a}$. We get

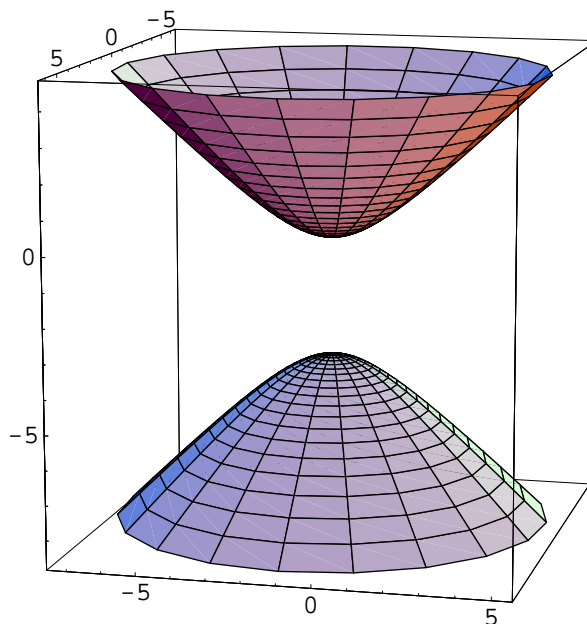
$$\begin{aligned}\vec{b} &= \langle 2, -5, 6 \rangle - \left\langle \frac{16}{9}, -\frac{16}{9}, -\frac{8}{9} \right\rangle \\&= \left\langle \frac{2}{9}, -\frac{29}{9}, \frac{62}{9} \right\rangle.\end{aligned}$$

4. Identify and sketch the quadric surface $x^2 + y^2 + 2y - z^2 - 4z = 0$.

Solution: We rewrite the equation as

$$x^2 + (y + 1)^2 = (z + 2)^2 - 3.$$

This is a (circular) hyperboloid of two sheets with axis parallel to the z -axis, center at $(0, -1, -2)$, and vertices at $-2 \pm \sqrt{3}$. Here is a sketch:



5. (a) Find the cylindrical and rectangular coordinates for the point whose spherical coordinates are $\rho = 3$, $\theta = \frac{\pi}{4}$, $\varphi = \frac{\pi}{6}$.

Solution: The cylindrical coordinates are

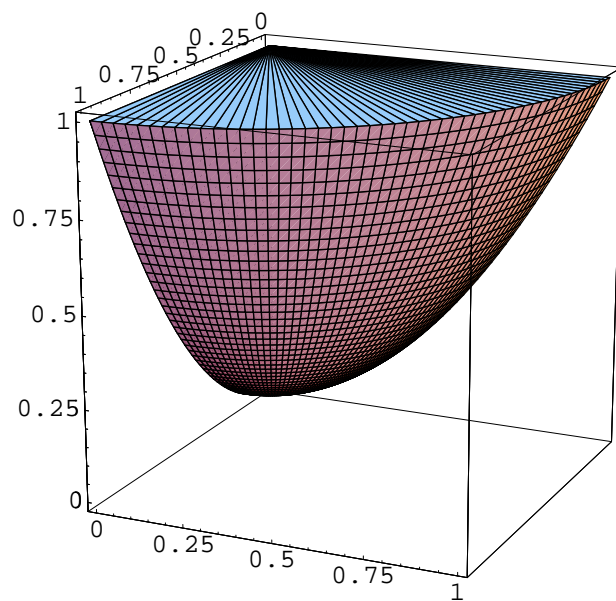
$$\begin{aligned} r &= \rho \sin \varphi \\ &= \frac{3}{2} \\ z &= \rho \cos \varphi \\ &= \frac{3\sqrt{3}}{2} \\ \theta &= \frac{\pi}{4}. \end{aligned}$$

The rectangular coordinates are

$$\begin{aligned} x &= r \cos \theta \\ &= \frac{3}{2} \frac{\sqrt{2}}{2} \\ &= \frac{3\sqrt{2}}{4} \\ y &= r \sin \theta \\ &= \frac{3}{2} \frac{\sqrt{2}}{2} \\ &= \frac{3\sqrt{2}}{4} \\ z &= \rho \cos \varphi \\ &= \frac{3\sqrt{3}}{2} \end{aligned}$$

- (b) Sketch the region described by $0 \leq \theta \leq \frac{\pi}{2}$, $0 \leq r \leq 1$, $r^2 \leq z \leq 1$.

Solution: This is the region in the first octant above the paraboloid $z = r^2$ and below the plane $z = 1$. Here is a sketch.



6. My motorcycle gets about 50 miles to the gallon. I use the trip odometer to keep track of how far I've ridden between refuelings. When the trip odometer reads about 100 miles, I stop for fuel, and the tank usually takes about 2 gallons.

Of course, the odometer doesn't always read exactly 100 miles at each fuel stop (there might not be a gas station right at that place in the road), and the tank doesn't always take exactly 2 gallons.

Let $f(m, g)$ denote the motorcycle's fuel economy (in miles per gallon) as a function of m , the number of miles driven, and g the number of gallons of fuel used. Find a linear function $L(m, g)$ that best approximates f when m is near 100 and g is near 2.

Solution: First we need the formula for f , which is clearly $f(m, g) = \frac{m}{g}$. From this we get

$$\begin{aligned}\frac{\partial f}{\partial m} &= \frac{1}{g}, \\ \frac{\partial f}{\partial g} &= -\frac{m}{g^2}.\end{aligned}$$

We evaluate these partials at the point in question to get

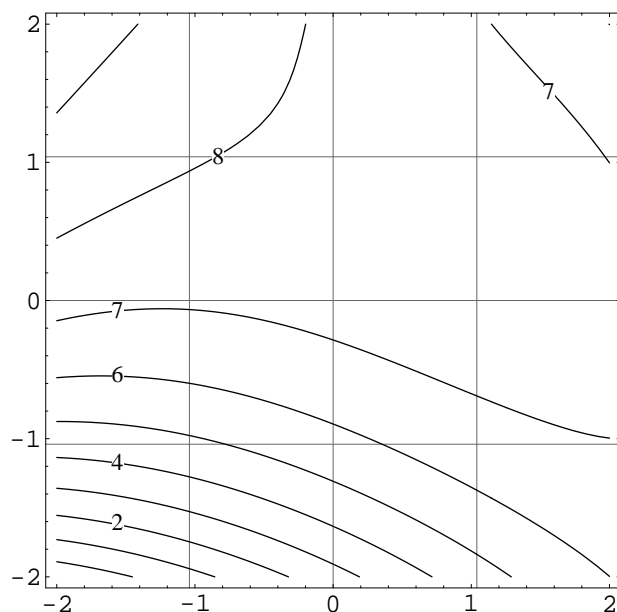
$$\begin{aligned}\left. \frac{\partial f}{\partial m} \right|_{(100, 2)} &= \frac{1}{2} \\ \left. \frac{\partial f}{\partial g} \right|_{(100, 2)} &= -25\end{aligned}$$

The linear function we want is

$$L(m, g) = 50 + \frac{1}{2}(m - 100) - 25(g - 2)$$

For each mile in excess of 100, we add $\frac{1}{2}$ mpg to our economy estimate; for each, say, tenth of a gallon in excess of 2.0 gallons, we subtract 2.5 mpg from our estimate.

7. Here is a contour plot of a function $f(x, y)$. Use the contour plot to construct a reasonable linear approximation to f at the point $(-1, -1)$.



Solution: From the picture, we see that $f(-1, -1)$ is somewhere between 4 and 5, and probably closer to 5. We estimate $f(-1, -1)$ as 4.8. The value of f_x at $(-1, -1)$ is positive, and we can estimate it by looking at the rate of change in f as we move to the right and left along the line $y = -1$. We guess that $f_x(-1, -1)$ is a little less than 1. Let's call it 0.8.

We can estimate $f_y(-1, -1)$ by looking at the rate of change in f as we move up and down along the line $x = -1$. Going upward from $(-1, -1)$, we see a rate of change that's probably between 2 and 3; going downward we find a rate of change that's between 3 and 4. Let's guess that $f_y(-1, -1)$ is about 3.

Our linear approximation is then

$$L(x, y) = 4.8 + 0.8(x + 1) + 3(y + 1).$$